

An inverse problem for Moore Gibson Thompson equation

arising in high intensity ultrasound



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- **Alberto Mercado**, Universidad Técnica Federico Santa María.
- **Sebastian Zamorano**, Universidad de Santiago.

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The model

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- Henceforth we will consider $\tau = 1$.

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- If $b = 0$, there does not exist an infinitesimal generator of the semigroup.
- If $\gamma := \alpha - \frac{c^2}{b} > 0$, the group associated to the equation is exponentially stable, and for $\gamma = 0$, the group is conservative.

Inverse Problem

The inverse problem is to recover the unknown coefficient $\alpha(x)$

$$\alpha(x) \rightarrow \begin{cases} u_{ttt} + \alpha u_{tt} - c^2 \Delta u - b \Delta u_t = f \\ u = g \\ u(\cdot, 0) = u_0, u_t(\cdot, 0) = u_1, u_{tt}(\cdot, 0) = u_2 \end{cases} \rightarrow u(\alpha)$$

from partial knowledge of some trace of the solution $u(\alpha)$ at the boundary, where $\Gamma_0 \subset \partial\Omega$ is a relatively open subset, called the observation region, and n is the outward unit normal vector on Γ .

$$\alpha \rightarrow \frac{\partial u(\alpha)}{\partial n} \text{ on } \Gamma_0 \times (0, T),$$

Under appropriate hypotheses:

- **Uniqueness:**

$$\frac{\partial u(\alpha_1)}{\partial n} = \frac{\partial u(\alpha_2)}{\partial n} \text{ on } \Gamma_0 \times (0, T) \text{ implies } \alpha_1 = \alpha_2 \text{ in } \Omega.$$

- **Stability:**

$$\|\alpha_1 - \alpha_2\|_{X(\Omega)} \leq C \left\| \frac{\partial u(\alpha_1)}{\partial n} - \frac{\partial u(\alpha_2)}{\partial n} \right\|_{Y(\Gamma_0)},$$

for some appropriate spaces $X(\Omega)$ and $Y(\Gamma_0)$.

- **Reconstruction:** Design an algorithm to recover the coefficient α from the knowledge of $\frac{\partial u(\alpha)}{\partial n}$ on Γ_0 .

- Third-order in time.
- Energies is not preserved, α represent a dissipation coefficient.
- M-G-T is not controllable with interior control.
- Improve the energies estimates.

Under certain conditions for α , Γ_0 and the time T .

The admissible coefficients:

$$\mathcal{A}_M = \left\{ \alpha \in L^\infty(\Omega), \quad \frac{c^2}{b} \leq \alpha(x) \leq M \quad \forall x \in \bar{\Omega} \right\}, \quad (4)$$

and we consider the assumptions:

$$\exists x_0 \notin \Omega \text{ such that } \Gamma_0 \supset \{x \in \Gamma : (x - x_0) \cdot n \geq 0\}, \quad (5)$$

and

$$T > \sup_{x \in \Omega} |x - x_0|. \quad (6)$$

Also, we suppose that the data satisfies

$$\begin{aligned} (u_0, u_1, u_2) &\in (L^2(\Omega) \times H^{-1}(\Omega) \times H^{-2}(\Omega)), \quad |u_2| \geq \eta > 0, \\ f &\in L^1(0, T; L^2(\Omega)), \quad g \in L^2(0, T; L^2(\partial\Omega)). \end{aligned} \quad (7)$$

Principal Results

Our main result, concerning the stability, is the following:

Theorem (R. L., A. Mercado, S. Zamorano)

Suppose that $\Gamma_0 \subset \partial\Omega$ and $T > 0$ satisfy (5)-(6) and the data satisfy (7). Let $M > 0$, and $\alpha_2 \in \mathcal{A}_M$ be such that the corresponding solution $u(\alpha_2)$ of (3) (with $\alpha = \alpha_2$) satisfies

$$u(\alpha_2) \in H^3(0, T; L^\infty(\Omega)).$$

Then there exists a constant $C > 0$ such that

$$C^{-1} \|\alpha_1 - \alpha_2\|_{L^2(\Omega)}^2 \leq \left\| \frac{\partial u(\alpha_1)}{\partial n} - \frac{\partial u(\alpha_2)}{\partial n} \right\|_{H^2(0, T; L^2(\Gamma_0))}^2 \leq C \|\alpha_1 - \alpha_2\|_{L^2(\Omega)}^2 \quad (8)$$

for all $\alpha_1 \in \mathcal{A}_M$.

- The hypothesis $u(\alpha_2) \in H^3(0, T; L^\infty(\Omega))$ in Theorem 1 is satisfied if more regularity is imposed on the data.

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- The hypotheses (5) and (6) on Γ_0 and T typically arises in the study of stability or observability inequalities for the wave equation.
- The assumption of the positiveness for u_2 appearing in Theorem 1 is classical when applying the Bukhgeim-Klibanov method and Carleman estimates for inverse problems with only one boundary measurement.

Theorem ([1], Theorem 2.2)

Let $b > 0$ and $\alpha \in L^\infty(\Omega)$. Then the solution $u(\alpha)$ is generated by a strongly continuous group on the state space

$$H = (H^2(\Omega) \cap H_0^1(\Omega)) \times H_0^1(\Omega) \times L^2(\Omega).$$

That is, for each $(u_0, u_1, u_2) \in (H^2(\Omega) \cap H_0^1(\Omega)) \times H_0^1(\Omega) \times L^2(\Omega)$ and $f \in L^1(0, T; L^2(\Omega))$, there exists a unique solution $U = (u(\alpha), u_t(\alpha), u_{tt}(\alpha)) \in C([0, T]; H)$.



Kaltenbacher, Barbara and Lasiecka, Irena

Exponential decay for low and higher energies in the third order linear Moore-Gibson-Thompson equation with variable viscosity

Palest. J. Math 1 (2012) 1–10.

Theorem (R. L., A. Mercado, S. Zamorano)

The unique solution

$(u, u_t, u_{tt}) \in C([0, T]; (H^2(\Omega) \cap H_0^1(\Omega)) \times H_0^1(\Omega) \times L^2(\Omega))$ of (3) satisfies

$$\frac{\partial u}{\partial n} \in H^1(0, T; L^2(\partial\Omega)). \quad (9)$$

Moreover, the normal derivative satisfies

$$\left\| \frac{\partial u}{\partial n} \right\|_{H^1(0, T; L^2(\partial\Omega))}^2 \leq C(\|u_0\|_{H^2(\Omega) \cap H_0^1(\Omega)}^2 + \|u_1\|_{H_0^1(\Omega)}^2 + \|u_2\|_{L^2(\Omega)}^2 + \|f\|_{L^1(0, T; L^2(\Omega))}^2). \quad (10)$$

Consequently, the mapping $(f, u_0, u_1, u_2) \mapsto \frac{\partial u}{\partial n}$ is linear continuous from $L^1(0, T; L^2(\Omega)) \times (H^2(\Omega) \cap H_0^1(\Omega)) \times H_0^1(\Omega) \times L^2(\Omega)$ into $H^1(0, T; L^2(\partial\Omega))$.

For $x_0 \in \mathbb{R}^N \setminus \overline{\Omega}$ and $\lambda > 0$, we define the weight functions ϕ and φ_λ as follows

$$\varphi_\lambda(x, t) = e^{\lambda\phi(x, t)}, \quad (11)$$

where

$$\phi(x, t) = |x - x_0|^2 - \beta t^2 + M_0, \quad 0 < \beta < 1, \quad (12)$$

and M_0 is chosen such that

$$\forall (x, t) \in \Omega \times (-T, T), \quad \phi(x, t) \geq 1. \quad (13)$$

Theorem (R. L., A. Mercado, S. Zamorano)

Suppose that Γ_0 and T satisfies (5)–(6). Let $M > 0$ and $\alpha \in \mathcal{A}_M$. Let $\beta \in (0, 1)$ such that

$$\beta T > \sup_{x \in \Omega} \|x - x_0\|. \quad (11)$$

Then, there exists $s_0 > 0$, $\lambda > 0$ and a positive constant C such that for all $s \geq s_0$

$$\begin{aligned} & \sqrt{s} \int_{\Omega} e^{2s\varphi\lambda(0)} |y_{tt}(0)|^2 dx \\ & + s\lambda c^4 \int_0^T \int_{\Omega} e^{2s\varphi\lambda} \varphi_{\lambda} (|y_t|^2 + |\nabla y|^2) dx dt + s^3 \lambda^3 c^4 \int_0^T \int_{\Omega} e^{2s\varphi\lambda} \varphi_{\lambda}^3 |y|^2 dx dt \\ & + s\lambda \int_0^T \int_{\Omega} e^{2s\varphi\lambda} \varphi_{\lambda} (|y_{tt}|^2 + |\nabla y_t|^2) dx dt + s^3 \lambda^3 \int_0^T \int_{\Omega} e^{2s\varphi\lambda} \varphi_{\lambda}^3 |y_t|^2 dx dt \\ & \leq C \int_0^T \int_{\Omega} e^{2s\varphi\lambda} |f|^2 dx dt + Cs\lambda \int_0^T \int_{\Gamma_0} e^{2s\varphi\lambda} (|\nabla y_t \cdot n|^2 + c^4 |\nabla y \cdot n|^2) d\sigma dt, \end{aligned}$$

for all $y \in L^2(0, T; H_0^1(\Omega))$ satisfying $f \in L^2(\Omega \times (0, T))$, $y(\cdot, 0) = y_t(\cdot, 0) = 0$ in Ω , and $y_{tt}(\cdot, 0) \in L^2(\Omega)$.

Sketch of the proof for Carleman estimates

For the wave equation we have

$$\begin{aligned} E_w(u) &:= \sqrt{s} \int_{\Omega} e^{2s\varphi\lambda(0)} |u_t(0)|^2 dx + s\lambda \int_0^T \int_{\Omega} e^{2s\varphi\lambda} \varphi_{\lambda} (|u_t|^2 + |\nabla u|^2) dx dt + s^3 \lambda^3 \int_0^T \int_{\Omega} e^{2s\varphi\lambda} \varphi_{\lambda}^3 |u|^2 dx dt \\ &\leq C \int_0^T \int_{\Omega} e^{2s\varphi\lambda} |L_0 u|^2 dx dt + Cs\lambda \int_0^T \int_{\Gamma_0} e^{2s\varphi\lambda} (|\nabla u \cdot n|^2) d\sigma dt, \end{aligned}$$

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where $L_0 u = u_{tt} - b\Delta u$ is the classical wave operator. We consider the operator $L_{\alpha} u = u_{ttt} + \alpha u_{tt} - c^2 \Delta u - b\Delta u_t$, and we have

$$L_{\alpha} u = L_0 u_t + \frac{c^2}{b} L_0 u + \left(\alpha - \frac{c^2}{b}\right) u_{tt}.$$

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$$L_{\alpha} u = L_0 u_t + \frac{c^2}{b} L_0 u + \left(\alpha - \frac{c^2}{b}\right) u_{tt}.$$

Now we consider the weight norm $\|f\|_w^2 = \int_0^T \int_{\Omega} e^{2s\varphi\lambda} |f|^2 dx dt$. And we compute

$$\|L_{\alpha} u - \left(\alpha - \frac{c^2}{b}\right) u_{tt}\|_w^2 = \|L_0 u_t\|_w^2 + \frac{c^4}{b^2} \|L_0 u\|_w^2 + 2\frac{c^2}{b} (e^{2s\varphi\lambda} \partial_t L_0 u, L_0 u).$$

Using the Carleman estimates for the wave equation,

$$C \|L_{\alpha} u\|_w^2 + C \left\| \left(\alpha - \frac{c^2}{b}\right) u_{tt} \right\|_w^2 \geq E_w(u_t) + \frac{c^4}{b^2} E_w(u) + \frac{c^2}{b} \int_0^T \int_{\Omega} e^{2s\varphi\lambda} \partial_t |L_0 u|^2 dx dt$$

Sketch of the proof for the stability Theorem

Bukhgeim-Klibanov method.

Algorithm to find the coefficient α

This algorithm will be based by the work of Baudouin, Buhan and Ervedoza [?], in which they propose a reconstruction algorithm for the potential of the wave equation.

Let us consider the following functional

$$J[\mu, f](y) = \frac{1}{2} \int_0^T \int_{\Omega} e^{2s\varphi_\lambda} |L_\alpha y - f|^2 dx dt + \frac{1}{2} \int_0^T \int_{\Gamma_0} e^{2s\varphi_\lambda} \left(\left| \frac{\partial y}{\partial n} - \mu \right|^2 + \left| \frac{\partial y_t}{\partial n} - \mu_t \right|^2 \right) d\sigma dt, \quad (12)$$

where $\alpha \in \mathcal{A}_M$, $g \in L^2(\Omega \times (0, T))$, $\mu \in H^1(0, T; L^2(\Gamma_0))$.

 [L. Baudouin, M. De Buhan, and S. Ervedoza.](#)

Global Carleman estimates for waves and applications.

Communications in Partial Differential Equations, 38(5):823–859, 2013.

Algorithm:

1 **Initialization:** $\alpha^0 = \frac{c^2}{b}$.

2 **Iteration:** From k to $k + 1$

Step 1 - Given α^k we consider $\mu^k = \partial_t \left(\frac{\partial u(\alpha^k)}{\partial n} - \frac{\partial u(\alpha)}{\partial n} \right)$ on $\Gamma_0 \times (0, T)$ where $u(\alpha^k)$ and $u(\alpha)$ are the solution of the problems

$$\begin{cases} L_{\alpha^k} u = f, \Omega \times (0, T) \\ u = g, \partial\Omega \times (0, T) \\ u(\cdot, 0) = u_0, u_t(\cdot, 0) = u_1, u_{tt}(\cdot, 0) = u_2, \Omega \end{cases} \quad (13)$$

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Step 2 - Minimize the functional $J[\mu^k, 0]$ on the admissible trajectories y .

Step 3 - Let $y^{*,k}$ the minimizer of $J[\mu^k, 0]$ and

$$\tilde{\alpha}^{k+1} = \alpha^k + \frac{y_{tt}^{*,k}(\cdot, 0)}{u_2}. \quad (15)$$

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Step 4 - Finally, consider $\alpha^{k+1} = T(\tilde{\alpha}^{k+1})$, where

$$T(\alpha) = \begin{cases} M & \text{if } \alpha > M \\ \alpha & \text{if } \frac{c^2}{b} \leq \alpha \leq M \\ \frac{c^2}{b} & \text{if } \alpha < \frac{c^2}{b}. \end{cases} \quad (14)$$

This function T is to guarantee at each step that α^k belongs to the admissible set \mathcal{A}_M .

The convergence of this algorithm

Theorem (R. L., A. Mercado, S. Zamorano)

Assume the same hypotheses of observability Theorem, and the following assumption of $u(\alpha)$:

$$u(\alpha) \in H^3(0, T; L^\infty(\Omega)) \text{ and } |u_2| \geq \eta > 0. \quad (15)$$

Then, there exists a constant $C > 0$ and $s_0 > 0$ such that for all $s \geq s_0$ and $k \in \mathbb{N}$

$$\int_{\Omega} e^{2s\varphi_{\lambda}(0)} (\alpha^{k+1} - \alpha)^2 dx \leq \frac{C}{\sqrt{s}} \int_{\Omega} e^{2s\varphi_{\lambda}(0)} (\alpha^k - \alpha)^2 dx. \quad (16)$$

Consider a new numerical approach

 Baudouin, L. and de Buhan, M. and Ervedoza, S.

Convergent Algorithm Based on Carleman Estimates for the Recovery of a Potential in the Wave Equation.

SIAM Journal on Numerical Analysis, 55(4):1578-1613, 2017.

Thank you for your attention!